EWS-102 CONTROL UNIT USER MANUAL

Product Overview

The EWS 102 Elevator Load Weighing Sysytem is a compact easy to install device that provides a comprehensive control system for use with a range of sensor/application types. The EWS 102 standard model monitors the elevator load and provides several alarm outputs. It automatically adjusts to prevent errors caused by friction/compensation chain, and includes intelligent software that enables it to auto zero calibrate when the elevator is inactive. The EWS 102 analog models perform all the functions of the standard model but provides pre torque control via a voltage or current analog output.

Fitting & Wiring

The EWS 102 can be mounted either on a DIN rail or on a flat surface (using a single screw mounting aperture in the rear plate).

Wire the chosen sensor type to the control unit (see separate data sheet for colour coding). Wire the control signal input to receive a suitable signal indicating the car has stopped at the landing with the doors opening or closing, for example the brake/open close circuit.

Wire the NO/NC alarm relays to each alarm input.

System Programming

Once you have fitted the system, power up the EWS 102 and configure it to the specific requirements of the installation. The EWS 102 is configured using straightforward step-by-step procedures using the LED screen and three multifunction keys as follows:

Entering System Setup/Calibration Modes

Press the Cal and Load buttons (display shows: <u>CAL</u>) and then press:

Cal for the system setup menu (display show [545])

Zero for zero calibration (display shows 2Ero)

[Load for load calibration (display shows [LDRd])

Navigation

Use the \clubsuit button to step through the menu items. Press \clubsuit to view the value of a menu item

Editing Values

When a value is displayed, use \Rightarrow to select each digit to edit (selected digit flashes) and use \clubsuit to step through the value for that digit. Once the required value is displayed press \bigcirc to save it.

The system will revert to the operational display after approx. 10 seconds. Alternatively, return to the display by pressing C twice.





EWS 102 Standard

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System Setup

Before starting the set up procedure, ensure that you have all the relevant data. Refer to the table and enter the required user values.

Setting	Meaning	Default Value	User Value	Connected to	Comment
CRP	Elevator capacity	1000kg		N/A	
AL I	Relay 1 trigger value	1100kg			Must be +ve value
RL2	Relay 2 trigger value	1000kg			Must be +ve value
AL 3	Relay 3 trigger value	-300kg			Can be +ve or -ve
HYSE	Amount load needs to drop after alarm to reset instrument	30kg		N/A	
ЧĽУ	Defines the delay in storing the car load value, after a signal has been applied to the EWS control signal input	2 sec		N/A	0=0sec, 1=0.5sec upto 7 = 3.5sec.
d iSP	Disable the display during travel	Off		N/A	
FLL	Defines the update rate and damping factor before the measured signal is stored	1			0=0.4sec, 1=0.8sec upto 3 = 1.6 sec.
5-65	Auto system reset function	Off			Must select On after calibration completed

Maximum Capacity

To set the maximum capacity of the elevator, enter the system setup menu and press 🕈 once to select the Maximum Capacity setting



Alarm Trigger Values

Each of the 3 alarm relays can be individually set to trigger at a particular load. Alarm relays 1 and 2 can trigger on any positive value. Typically, relay 1 would be set to trigger the required overload condition, which prevents the elevator doors from closing. When relay 1 is triggered, the internal buzzer also sounds.

Relay 3 van be set to trigger at either a positive or negative value. The negative value can be used to indicate the presence of an obstruction affecting the free movement of the cabin.

Note: When setting a positive value. for Alarm 3, ensure that the left hand digit is set to '0' if it is set to '-' the value will be treated as a negative



Press \blacklozenge to view the current value. Change the value using the \blacklozenge and \blacklozenge buttons and then press \bigcirc to save the new setting and move to the next parameter.

Hysteresis Value

Once an alarm has been triggered, it will not reset until the load has dropped below the trigger value by the hysteresis value set here. This prevents cycling of of the alarm.

To set the hysteresis value. enter the system setup menu and press the 🕈 button repeatedly until the hysteresis menu is displayed



Press \Rightarrow to view the current value. Change the value using the \Rightarrow and \clubsuit buttons and then press \bigcirc to save the new setting and move to the next parameter.



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Delay

To adjust the time interval from when the door close signal is activated and the measured load is stored by the EWS 102, to minimise signal spikes due to the mechanical shock effect of the door closing.



Defines the time from the control signal input is activated and the car load is stored. Default =2, the available settings are: $0 = 0 \sec, 1 = 0.5 \sec, \dots, 7 = 3.5 \sec$.

Display

Option for turning the display on or off when the lift is moving, activated by the the door close signal



To change the setting, press \blacklozenge and use \blacklozenge to toggle beteween On and OFF.

Filter Value

The filter value determines the update rate and damping factor. The available settings are:

0 = 0.4sec, 1 = 0.8sec, 2 = 1.2sec, 3 = 1.6sec. To set the filter value, enter the system setup menu and press the \clubsuit button repeatedly until the hysteresis menu item is displayed:



Press \Rightarrow to view the current value. Change the value using \Rightarrow and \clubsuit buttons, then press \bigcirc to save the new setting and move to the next parameter.

Sounder Control

An internal sounder beeps when an overload alarm is triggered or when the keypad is pressed



To change the settings, press \Rightarrow and use \blacklozenge to toggle between ON and OFF. Press \bigcirc to save the new setting and exit System Setup

System Reset

Option for turning the auto system reset on or off, this should always be OFF during calibration and On before the lift enters service.



To change the settings, press \Rightarrow and use \uparrow to toggle between ON and OFF. Press \bigcirc to save the new setting and exit System Setup

Calibration

Before starting to, ensure that you have suitable known weight available for calibrating the load.

To enter calibration mode you must fit a link between the Control Signal Input terminals:

Zero Calibration

To enter Zero Calibration mode (Press Cal and Load buttons together followed by Zero)



Ensure that the cabin is empty and press at to initiate the calibration. The display will count down from 10 to 1 and then displays *LAL* to indicate that the zero point has been calibrated and stored. Press *Zero* within 10 seconds to proceed to the Load calibration mode.

Load Calibration

If you press Load within 10 seconds at the end of the last procedure, press Cal and Load buttons together followed by Load to enter Load Calibration Mode.



Place the known load into the cabin and press [Cal]



Enter the weight of the known load in kg using the \Rightarrow and \clubsuit buttons, then press \bigcirc to complete the input and start the calibration the display will countdown from 10 to 1 and then displays $\boxed{\Box RL}$ to indicate the load has been calibrated.



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Error Codes

If after powering up the unit, the display shows an error message, this could indicate that the sensor positioning and/or wiring needs to be checked.

Code	Error	Cause/Solution
Err I	Sensor Signal Input - Negative	Reverse connect
Err2	Insufficient Sensor Signal	Installation Error
Err3	Sensor Offset Too High - Positive	Installation Error
Err4	Sensor Offset Too High - Negative	Installation Error
ErrS	Trying to calibrate without Control Signal link	Fit link between
Еггб	Sensor not conected to EWS	Connect sensor/

Reverse connection of sensor signal leads
Installation Error - Contact Garan
Installation Error - Contact Garan
Installation Error - Contact Garan
Fit link between control signal terminals
Connect sensor/check sensor wiring

Analog Output Variants

Depending on the EWS variant these control units can provide an analog output proportional to the elevator load and provide a signal to allow the controller to pre-torque the motor. Analog outputs - current (4-20mA, 0-20mA), voltage (0-5V, 0-10V, +/-5V or +/-10V) or current (4-20mA) only.

EWS-102 4-20mA Version

For further information please refer to EWS-102 4-20mA Control Unit Supplementary Information Sheet.

EWS-102 Multi Analog Version

For information regarding selction of the required analog output please refer to EWS-102 Control Unit Multi Analog System Setup Sheet.



Note:

The analogue output section is galvanically isolated from the instrument power, hence the separate field supply.

If isolation isn't required, the instrument power supply can also be the field power supply.

Intelligent Software

The EWS 102 Intelligent software features:

An AUTO ZERO function that is pre-set and designed to remove any zero drift errors as a result of ambient 1. changes.

2. A SYSTEM RESET function which is user defined and will re-zero the overload system when the elevator is at rest.

To set the System Reset values, enter the system setup menu and press the button repeatedly until the first of these parameters are displayed.

Travel Compensation

The travel compensation prevents errors associated with the presence of a compensation chains. It is automatically activated when the Control Signal input is wired to receive a door open/close signal.

